

# algorithms and data structures (shortest path)

amir yehudayoff

# shortest paths

finding shortest paths is an important task

maps

make decisions

explore domain

## shortest paths

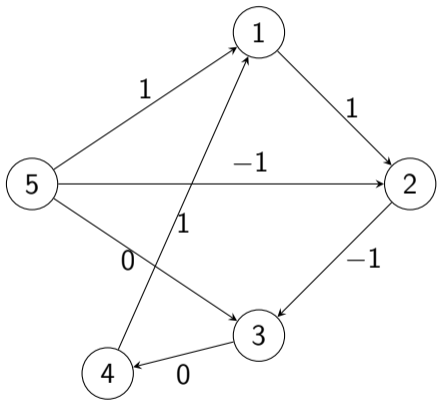
efficient algorithms for distances in graph (Dijkstra)

**what if not a distance?**

## weighted graphs

let  $G = (V, E)$  be a directed graph  
let  $w : E \rightarrow \mathbb{R}$  be a weight function

**remark:** possibly negative

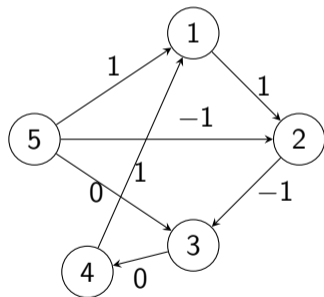


## path weights

the weight of a path  $\gamma = (v_0, v_1, \dots, v_m)$  is

$$w(\gamma) = \sum_{i=1}^m w(v_i, v_{i-1})$$

**example:** weight of 5, 2, 3, 4?



## “distances”

the weight of a path  $\gamma = (v_0, v_1, \dots, v_m)$  is  $w(\gamma) = \sum_{i=1}^m w(v_i, v_{i-1})$

the “distance”

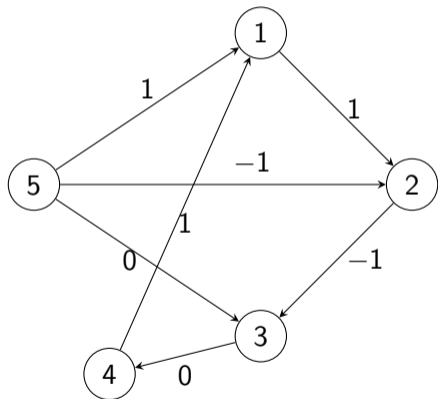
$$d(u, v) = \min\{w(\gamma) : u \xrightarrow{\gamma} v\}$$

### remarks:

not a distance!

could be  $-\infty$

$d(5, 4) = ?$



## task

### input

digraph  $G = (V, E)$

weights  $w : E \rightarrow \mathbb{R}$

source  $s \in V$

### output

$v \mapsto d(s, v)$  or “negative cycle”

## Bellman-Ford

for  $v \in V$  set  $d_0(v) = \infty$

for  $k = 0, 1, \dots, n - 1$  set  $d_k(s) = 0$

for  $k = 0, 1, \dots, n - 2$

  for  $(u, v) \in E$

    set  $d_{k+1}(v) = \min\{d_k(v), d_k(u) + w(u, v)\}$

for  $(u, v) \in E$

  if  $d_{n-1}(v) > d_{n-1}(u) + w(u, v)$  return “negative cycles”

return  $d_{n-1}$

**initialization**

for  $v \in V$  set  $d_0(v) = \infty$

**know**

for  $k = 0, 1, \dots, n - 1$  set  $d_k(s) = 0$

**update**

for  $k = 0, 1, \dots, n - 2$

for  $(u, v) \in E$

set  $d_{k+1}(v) = \min\{d_k(v), d_k(u) + w(u, v)\}$

**sanity check**

for  $(u, v) \in E$

if  $d_{n-1}(v) > d_{n-1}(u) + w(u, v)$  return “negative cycles”

return  $d_{n-1}$

compute  $d_1, d_2$

for  $v \in V$  set  $d_0(v) = \infty$

for  $k = 0, 1, \dots, n - 1$  set  $d_k(s) = 0$

for  $k = 0, 1, \dots, n - 2$

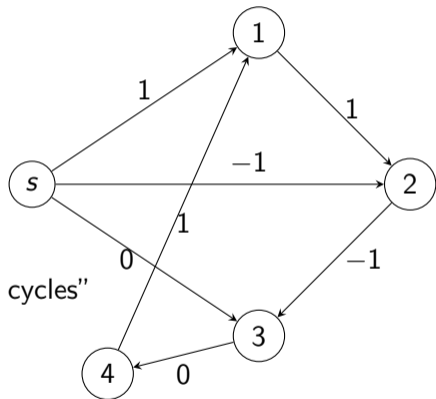
for  $(u, v) \in E$

set  $d_{k+1}(v) = \min\{d_k(v), d_k(u) + w(u, v)\}$

for  $(u, v) \in E$

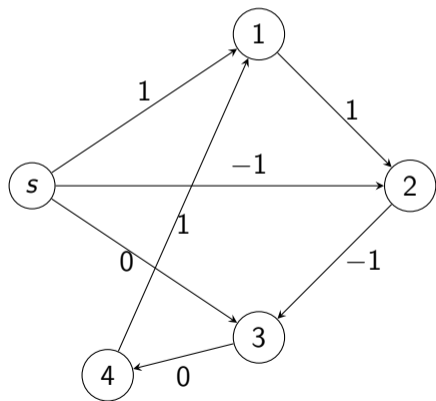
if  $d_{n-1}(v) > d_{n-1}(u) + w(u, v)$  return "negative cycles"

return  $d_{n-1}$



compute  $d_1, d_2$

	$d_0$	$d_1$	$d_2$
s	0	0	0
1	$\infty$	1	1
2	$\infty$	-1	-1
3	$\infty$	1	-2
4	$\infty$	$\infty$	0



## running time

### **observation**

the running time of Bellman-Ford is  $O(|V| \cdot |E|)$

**define**

for integer  $k$

$\delta_k(v)$  is the minimum weight of a path  $s \rightarrow v$  of length  $\leq k$

(if no path  $\infty$ )

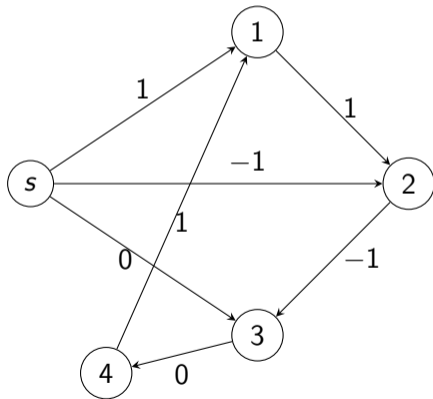
**remarks**

finite “proxy” for  $d$

not  $-\infty$

$\delta_k$ 

$$d(s, 3) = -2 \quad \delta_0(3) = \infty \quad \delta_1(3) = 0 \quad \delta_2(3) = -2$$



**claim**

if there are no negative cycles in  $G, w$  then for all  $v$

$$\delta_{n-1}(v) = d(s, v)$$

**proof**

with no negative cycles minimum weight path is simple

length of simple path  $\leq n - 1$

loop

**claim**

for every  $k \geq 0$  and for all  $v$

$$d_k(v) = \delta_k(v)$$

**proof?**

## induction

**claim**  $d_k(v) = \delta_k(v)$

**proof**

base:  $k = 0$  is true

step: assume it is true for  $k \dots$

## induction

**claim**  $d_k = \delta_k$  assuming  $d_{k-1} = \delta_{k-1}$

**proof**

for vertex  $v$  there are two options

$$\delta_k(v) = \infty$$

$$\delta_k(v) < \infty$$

## induction

**claim**  $d_k = \delta_k$  assuming  $d_{k-1} = \delta_{k-1}$

**proof** for vertex  $v$  so that  $\delta_k(v) = \infty$

$$\delta_{k-1}(v) = \infty$$

for all  $u$  so that  $(u, v) \in E$   $\delta_{k-1}(u) = \infty$

algorithm is  $d_k(v) = \min\{d_{k-1}(v), d_{k-1}(u) + w(u, v)\}$

so  $d_k(v) = \infty$

## induction

**claim**  $d_k = \delta_k$  assuming  $d_{k-1} = \delta_{k-1}$

**proof** for vertex  $v$  so that  $\delta_k(v) < \infty$

let  $\gamma$  be a minimum weight path  $s \rightarrow v$  of length  $\leq k$

let  $u$  be so that  $\gamma$  is  $s \rightarrow \dots \rightarrow u \rightarrow v$

## induction

**claim**  $d_k = \delta_k$  assuming  $d_{k-1} = \delta_{k-1}$

**proof**

$\gamma$  is minimum weight  $s \rightarrow v$  of length  $\leq k$  and  $u$  before  $v$  in  $\gamma$

by minimality and induction

$$\delta_k(v) = \delta_{k-1}(u) + w(u, v) = d_{k-1}(u) + w(u, v)$$

by algorithm

$$d_k(v) \leq d_{k-1}(u) + w(u, v)$$

so  $d_k(v) \leq \delta_k(v)$

## induction

**claim**  $d_k = \delta_k$  assuming  $d_{k-1} = \delta_{k-1}$

**proof**

proved  $d_k(v) \leq \delta_k(v)$  and other direction remains

by minimality for all  $r$  such that  $(r, v) \in E$

$$\delta_k(v) \leq \delta_{k-1}(r) + w(r, v)$$

by induction

$$\delta_k(v) \leq d_{k-1}(r) + w(r, v)$$

$$\delta_k(v) \leq \delta_{k-1}(v) = d_{k-1}(v)$$

by algorithm  $\delta_k(v) \leq d_k(v)$

## the process

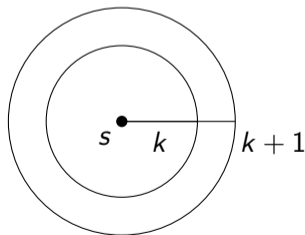
### claim

for every  $k \geq 0$  and for all  $v$

$$d_k(v) = \delta_k(v)$$

### idea

at time  $k$  we fully explored the “ $k$ -ball around  $s$ ”



**corollary**

if there are no negative cycles in  $G, w$  then

$$d_{n-1}(v) = \delta_{n-1}(v) = d(s, v)$$

**proof**

two equalities from previous claims

## the check I

### **claim**

if the algorithm did not report “negative cycle” then there are no negative cycles (reachable from  $s$ )

**claim**

if the algorithm did not report “negative cycle” then there are no negative cycles (reachable from  $s$ )

**proof** let  $v_0 \rightarrow v_1 \rightarrow \dots \rightarrow v_m = v_0$  be a cycle reachable from  $s$

by corollary and assumption  $d_{n-1}(v_{i+1}) \leq d_{n-1}(v_i) + w(v_i, v_{i+1})$

summing

$$\sum_{i=0}^{m-1} d_{n-1}(v_i) = \sum_{i=0}^{m-1} d_{n-1}(v_{i+1}) \leq \left( \sum_{i=0}^{m-1} d_{n-1}(v_i) \right) + w(\text{cycle})$$

## the check II

### **claim**

if the algorithm reported “negative cycle” then there is a negative cycle

**claim**

if the algorithm reported “negative cycle” then there is a negative cycle

**proof (contra positive)** assume there are no negative cycles

so for all  $v$

$$d_{n-1}(v) = \delta_{n-1}(v) = d(s, v)$$

the algorithm does not report “negative cycle” because for every  $(u, v) \in E$

$$d(s, v) \leq d(s, u) + w(u, v)$$

### theorem

if there are no negative cycles in  $G, w$  then output  $v \mapsto d(s, v)$

if there are negative cycles reachable from  $s$  then output “negative cycle”

the running time is  $O(|V| \cdot |E|)$

## the process

**goal:** compute  $d(s, v)$  on a weighted graph  $G$

**process:** iteratively produces better and better approximations

$$d_0, d_1, d_2, \dots$$

where  $d_0$  contains no info and  $d_{k+1}$  is built from  $d_k$

after  $n - 1$  iterations we reach the goal (or abort)

## optimization

we have a collection of objects  $P$

usually  $P$  is “huge”

each object has a weight  $w : P \rightarrow \mathbb{R}$

wish to compute  $\min\{w(p) : p \in P\}$  or find a minimizer

**example:**  $P$  is paths in digraph weighted by  $w : E \rightarrow \mathbb{R}$

# optimization

wish to compute  $\min\{w(p) : p \in P\}$

when can we hope to do this efficiently?

what are the algorithmic principles?

# optimization

wish to compute  $\min\{w(p) : p \in P\}$

when can we hope to do this efficiently?

what are the algorithmic principles?

greedy algorithm

divide and conquer

dynamic programming

## greedy algorithm

wish to compute  $\min\{w(p) : p \in P\}$

**example: the cube**

$$P = \{0, 1\}^n$$

and

$$w(p_1, \dots, p_n) = \sum_i w_i p_i$$

for some known  $w_1, \dots, w_n$

## divide and conquer

wish to compute  $\min\{w(p) : p \in P\}$

**example: intervals**

$$P = \{[a, b] : 1 \leq a \leq b \leq n\}$$

and

$$w([a, b]) = \sum_{a \leq i \leq b} w_i$$

for some known  $w_1, \dots, w_n$

## dynamic programming

wish to compute  $\min\{w(p) : p \in P\}$

**example: distances**

$$P = \{\text{paths in digraph}\}$$

and

$$w : E \rightarrow \mathbb{R}$$

# dynamic programming

wish to compute  $\min\{w(p) : p \in P\}$

## **DP is used when**

objects in  $P$  can be broken into local pieces

the total cost can be derived from the local costs

a local optimal solution is used in many other solutions

global optimality implies local optimality

(this is not a mathematical statement)

## dynamic programming (DP)

wish to compute  $\min\{w(p) : p \in P\}$

if  $P$  is paths in digraph weighted by  $w : E \rightarrow \mathbb{R}$  then

weight of a path is sum of its edges

a subpath of an optimal path is an optimal path

an optimal path can be used in many “larger paths”

## summary

discrete optimization

greedy

divide and conquer

dynamic programming

all pairs

to compute all pairwise distances using Bellman-Ford the time is

$$O(n \cdot n^3) = O(n^4)$$

## all pairs

to compute all pairwise distances using Bellman-Ford the time is

$$O(n \cdot n^3) = O(n^4)$$

we can do better...

## all pairs

think of weights as a matrix  $W = (W_{u,v})$

define matrix product

$$(A \star B)_{u,v} = \min\{A_{u,r} + B_{r,v} : r \in V\}$$

---

<sup>1</sup>when there are no negative cycles

## all pairs

think of weights as a matrix  $W = (W_{u,v})$

define matrix product

$$(A \star B)_{u,v} = \min\{A_{u,r} + B_{r,v} : r \in V\}$$

**claim**  $W^{\star n}$  contains all pairwise distances<sup>1</sup>

---

<sup>1</sup>when there are no negative cycles

think of weights as a matrix  $W = (W_{u,v})$

define matrix product

$$(A \star B)_{u,v} = \min\{A_{u,r} + B_{r,v} : r \in V\}$$

**claim**  $W^{\star n}$  contains all pairwise distances<sup>1</sup>

**running time** repeated squaring

$$M_1 = W \quad \text{and} \quad M_{k+1} = M_k \star M_k$$

takes time  $O(n^3 \log n)$

---

<sup>1</sup>when there are no negative cycles

## summary

efficient algorithm for shortest path for general weighted digraphs

dynamic programming

iteratively improving a solution to optimization problem

iterated matrix product